

# mL-TCR4 TEMPERATURE CONTROLLER



mL-TCR4 Temperature Controller

- 4 d g ts d splay
- Temperature sensor nput (TC / RTD)
- Adjustable Process Offset Value
- Programmable ON/OFF, P. Pl. PD & PID control types
- Adaptat on of PID coeff c ents to the system by Auto Tune/Self Tune
- Programmable control and alarm functions for control outputs

The mL-TCR4 temperature controllers are designed for measuring and controlling a temperature value in industry. They can be used in many applications with their TC and RTD temperature measurement input, mult -funct on control outputs, programmable control and alarm funct ons. They are manly used n glass, plast c, petro-chem stry, text le, automot ve and machine production industries. Accurate and advanced controlling is performed with selectable ON-OFF, P, PI, PD, PID, Self Tune PID, Auto Tune PID funct ons.

# SPECIFICATIONS

# INPUT

Process Input: TC/RTD

Thermocouple (TC): J, K, R, S, T and L (IEC584.1)(ITS90)
Thermores stance (RTD): Cu-50 and Pt100 (IEC 751) (ITS90)
Measurement Range: Please refer to parameter PUB n parameters sect on.

Accuracy: ± 0.25% of scale for thermocouple and thermores stance.

Cold Junct on Compensat on: Automat cally ±0.1°C/1°C

L ne Compensat on: Max mum 10 Ohm

Sensor Break Protect on: Upscale

Sampl ng Cycle: 0.1 second

CONTROL

Control Forms: ON/OFF, P. Pl. PD or PID (Control form can be programmed by the user.)

Process Output: Relay(7A@250VV at res st ve load) or SSR Dr ver Output (Max mum 10mA, Max. 17VZ )

Alarm Output: Relay (7A@250VV at res st ve load)

# SUPPLYVOLTAGE

115VV (±15%) 50/60Hz - 3VA

### DISPLAY

Temperature D splay: 16 mm Red 4 d g ts LED D splay

Led Ind cators: O1 (Relay Process Output Status LED), O2 (SSR Process Output Status LED), P(Programm ng Mode LED), S(Set Value LED), C, F LEDs

# ENVIRONMENTAL RATINGS and PHYSICAL SPECIFICATIONS

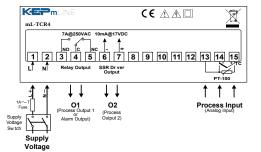
Operat ng Temperature: 0...50°C Hum d ty: 0-90%RH (none condens ng) Protect on Class: IP65 at front, IP20 at rear

We ght: 350 gr.

**D mens on:** 96 x 96 mm, Depth: 100 mm

Panel CutOut: 92 x 92 mm

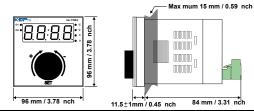
# Electr cal W r ngs



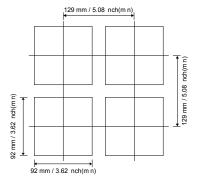
To reduce the effect of electrical noise on device, low voltage line (especially sensor nput cables) wrng must be separate from high current and voltage line. If poss ble, use shelded cable and sheld must be connected to ground only on one s de.

### D mens ons

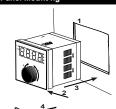
CE



# Panel Cut-out

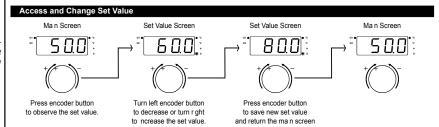


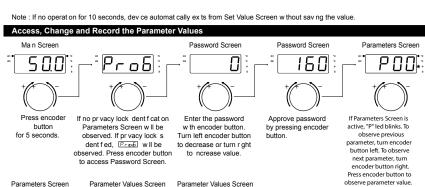
# Panel Mount ng

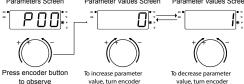


- 1- Before mount ng the dev ce n your panel, make sure that the cutouts are the rght sze.
- 2- Check front panel gasket post on.
- 3- Insert the device through the cutout. If the mount no clamps are on the un t. remove them before nsert ng the un t to the panel.
- 4- Insert the mount ng clamps in the des gnated holes that are located on four s des of dev ce.
- 5- Drag the mount ng clamps in direction 5 unt I the dev ce is completely mmob le within the panel.
- 6- In order to remove device push on the mount ng clamp as shown with arrow 6 and pull back.

# Front Panel Def n t on Status of Control Output 1 (Relay)-Temperature Un t Ind cator Status of Control Output 2 (SSR) Temperature Un t Ind cator Programm ng Mode Ind cator Set Value Ind cator Encoder Button

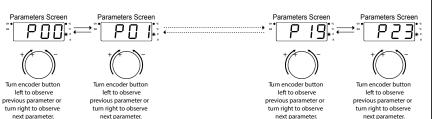






to observe value, turn encoder button left. Press encoder the parameter value. button right. Press encoder button to save

Note1: PID control parameters ( P 1 1, P 12, P 13, P 14, P 15, P 18 ) are not seen when PDB parameter s set as one? Note2: On Off control parameters ( Pgg , P Ig) are not seen when output control type parameter (PG) set as  $P \cdot d$ . Note3: Alarm parameters ( $P \cdot 17$ ,  $P \cdot 18$ ,  $P \cdot 19$ ,  $P \cdot 20$ ,  $P \cdot 2 \cdot 1$ ,  $P \cdot 2 \cdot 2$ ) are not seen when output type parameter (PG) set as  $P \cdot 2 \cdot 3$ . Note4: Alarm parameters(P 18, P 19, P20, P2 1, P22) are not seen when alarm type parameter ( P 17) s set as no. Note5: If P 2 3 s d fferent from 0 and user enters 0 on password screen, parameter values are observed but can not be changed



Note: If no operat on for 20 seconds on Parameters Screen, device automatically return Main Screen

Instruct on Manual: mL-TCR4 990954 11/01/18

# Parameters Descriptions

Pfff : Process input type selection parameter. (Default: ff )

## : J type (Fe,Cu,Ni) Thermocouple; -200°C,900°C; -328°F,1652°F

1: J type (Fe,Cu,Ni) Thermocouple; -199.9°C,900.0°C; -199.9°F,999.9°F

2 : K type (Ni,Cr,Ni) Thermocouple; -200°C,1300°C ; -328°F,2372°F

3 : K type (Ni,Cr,Ni) Thermocouple; -199.9°C,999.9°C ; -199.9°F,999.9°F

Y: R type (Pt13%RhPt) Thermocouple: 0°C.1700°C: 32°F.3092°F

5 : R type (Pt13%RhPt) Thermocouple; 0.0°C,999.9°C ; 32.0°F,999.9°F

δ : S type (Pt10%RhPt) Thermocouple; 0°C,1700°C; 32°F,3092°F 7 : S type (Pt10%RhPt) Thermocouple: 0.0°C 999.9°C : 32.0°E 999.9°E

8 : T type (Cu,Cu,Ni) Thermocouple; -199°C,400°C; -199°F,752°F

9: T type (Cu,Cu,Ni) Thermocouple; -199.0°C,400.0°C; -199.0°F,752.0°F

10: L type (Ni,Cr,Co/Ni,Fe,Mn,Cu) Thermocouple; -150°C,800°C; -199°F,999°F

/ /: L type (Ni,Cr,Co/Ni,Fe,Mn,Cu) Thermocouple; -150.0°C,800.0°C;-199.0°F,999.0°F

;2 : Cu-50 Thermoresistance; -199°C,200°C ; -199°F,392°F

/3 : Cu-50 Thermoresistance; -199.0°C,200.0°C; -199.0°F,392.0°F

/Y: PT100 Thermoresistance; -200°C,650°C; -328°F,1202°F !5 · PT100 Thermoresistance: -199 9°C 650 0°C · -199 9°F 999 9°F

 $\rho_{0}^{\alpha}$ : Unit selection parameter.  ${}^{\alpha}$ E or  ${}^{\alpha}$ F can be chosen. (Default:  ${}^{\alpha}$ E)  $\rho_{0}^{\alpha}$ E: Operation scale minimum(Low Limit) value. It changes according to the process input type and scale. (Default: -200)

Pff : Operation scale maximum(High Limit) value. It changes according to the process input type and scale. (Default: 900)

PAY: Process set value low limit parameter. It can be adjusted between Operation Scale Minimum( P(1)) and Process Set Value High Limit( P(1)). (Default: -200)

P05: Process set value high limit parameter. It can be adjusted between Process Set Value Low Limit( 2014) and Operation Scale Maximum( 2013). (Default: 900)

PDS: Process offset value. It can be adjusted as a degree (of or of), from -10% of scale to 10% of scale. It is added to the process display value. (Default: 0)

Pil 7: Process output type. Process output can be selected Relay( rt y ) or SSR(55c), (Default;55c)

PAR : Output control type selection. It can be selected onof or P.d. (Default: onoF)

PG9: Hysteresis value. It can be adjusted from 1°(point representation is 0.1°) to 20°. (Default: 3)

P !!! : Minimum ON/OFF control output time parameter. It can be adjusted from 0 to 60 seconds. (Default: 0)

P!: Proportional band (P) value. It can be adjusted from %1.0 to %100.0. (Default: 10.0)

P : Proportional Period (Output Control Period). If control output is SSR, It can be adjusted from 0.5 to 150.0 seconds. If control output is Relay, It can be adjusted 60.0 to 150.0 seconds. (Default: 10.0)

P13: Proportional Offset value. This parameter is used for shifting the proportional band. It can be adjusted as a degree(of or of), from (-Operation

Scale Maximum /2) to (Operation Scale Maximum /2). (Default: 0) P 14: Integral Time. It can be adjusted from 0 to 3600 seconds.

(Default: 100) P 15: Derivative Time. It can be adjusted from 0.0 to 999.9 seconds. (Default: 25.0)

P 16: If tune parameter is set as SELF or RULo, device starts to calculate PID parameters automatically. (Defaultno )

. Device does not calculate PID parameters

§§§§§ : Step Response Tuning operation.

Ruto: Limit Cycle Tuning operation.

P 17: Alarm type selection.(Default: PR 8)

P 18: Alarm set value parameter. It can be adjusted between Operation Scale Minimum to Operation Scale Maximum. (Default: 300)

P !9: Alarm hysteresis value. It can be adjusted from 1° (point representation: 0.1°) to 50% of scale. (Default: 3)

PPM: Alarm on delay time. It can be adjusted from 0 to 9999 seconds. (Default: 0)

P2 1: Alarm off delay time. It can be adjusted from 0 to 9999 seconds. (Default: 0)

P22: Alarm opening delay time. It can be adjusted from 0 to 9999 seconds (Default: 0)

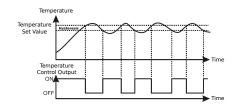
P23: Password for accessing to the parameters section. It can be adjusted from 0 to 9999. If parameter value is  $\hat{u}$  , password screen is not seen. If parameter value is different from !! and :

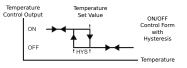
-If user enters different value from saved value, device will return to mair screen automatically

-If user enters  $\hat{\mathcal{G}}$  , all parameters can be observed except P23 . But device does not allow to do any changes in parameters. (Default:  $\Omega$ 

# Adjustment of Hysteresis Value for ON/OFF Control

In ON/OFF control algorithm, temperature value tries to keep equal to set value by opening or closing completely last control element. ON/OFF controlled system, temperature value oscillates continuously. Temperature value's oscillation period or amplitude around set value changes according to controlled system. For reducing oscillation period of temperature value, a threshold zone is formed below or around set value and this zone is named hysteresis. Action of control output is described with figures below.





# Tune Operation

Starting the Tune operation

1- Enter the P 15 parameter and select SELF or RULe . Observe that tunk blinks. (If SELF is selected and start conditions are not okay for Tune operation, Effective for the selected and start conditions are not okay for Tune operation, Effective for the selected and start conditions are not okay for Tune operation, Effective for the selected and start conditions are not okay for Tune operation, Effective for the selected and start conditions are not okay for Tune operation. blinks during 10 seconds )

2- Device calculates PID control coefficients and sets the process value to wanted value.

Cancelling tune operation:

1- If sensor breaks;

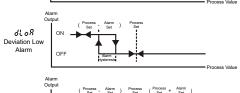
2- If tune operation can not be completed in 8 hours;

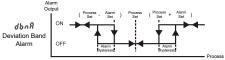
3- While tune operation is running, if process value becomes greater than process set value:

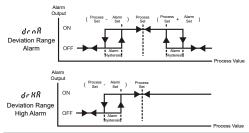
4- While tune operation is running, if user changes the process set value;

6- While tune operation is running, if user changes the parameter in menu; Then tune operation is canceled and device continues to run with former PID parameters without changing PID parameters.

# Alarm Types Outpu 8.89 Process High Alarm Output PLOR Process Low OFF Alarm AH IA Deviation High Alarm







# Error Messages



Sensor failure in analog inputs. If there is no sensor connection or the value that is read from the analog input goes out of the device scale, warning is observed

If one of the alarm types in the alarm parameter ( P ! ? ) is selected and the alarm condition has occurred, the temperature value is displayed alternately with RL message on display.





Tune failure. If SELF is selected in PID Tune Parameter( P 18 ) and start conditions are not okay for Tune operation, the temperature value is displayed alternately with \$\xi\_{er}\$ message on display during 10 seconds.

# Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

-One piece unit

Two pieces mounting clamp

A visual inspection of this product for possible damage occurred during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and the electrical connection of the device from

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

Do not use the unit in combustible or explosive gaseous atmospheres. During the equipment is put in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

T[\*] ca\* of the product on a system must be done with it's mounting clamps. Do not mount the device with inappropriate mounting clamps. Be sure that the device will not fall while mounting. It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

# Warranty

Kessler-Ellis Products warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date.

This warranty is in force if duty and responsibilities which are determined in warranty document and instruct on manual performs by the customer completely.

# Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts. Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic

# Other Information

#### Manufacturer Information:

Kessler-Ellis Products, Inc.

10 Industrial Way East, Eatontown, NJ 07724

Phone: 732-935-1320 • Fax: 732-935-9344 www.KFPml INF.com

### Repair and Maintenance Service Information:

If you are in need of repair or maintenance service please call to acquire a Return Goods Authorization (RGA) number. Or fill out a form on our website. Phone: 732-935-1320 • Fax: 732-935-9344 www.KEPml.INF.com

# Ordering Information

# mL-TCR4

Time Controller with 110 VAC Power, Programmable Input Type for Thermocouple or RTD (See Parameters POD), Relay Output and SSR Output.



Before commissioning the device, parameters must be set in accordance with desired use. Incomplete or incorrect configuration can cause dangerous stiuations.



Because of limited mechanical life of relay output contact, SSR output is recommended which the device use PID control The device with ON/OFF control algorithm, hysteresis parameter must be set a suitable value for your system, to avoid too much relay switching.



⇒ Vdc or Vac can be applied.



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